PROCEEDINGS OF SCIENCE

The first joint observation by KAGRA with GEO 600

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KAGRA conducted its first joint observation with GEO 600 for two weeks in April, 2020. We performed two types of all-sky searches and two searches dedicated to gravitational wave signals associated with gamma-ray burst events observed during the run. We did not detect any gravitational wave signals, which was expected given the sensitivity of both detectors at that time. However, we did confirm that several search pipelines used in the LIGO-Virgo-KAGRA collaborations worked effectively on the KAGRA data. In this proceeding, we will summarize the data quality of detectors and the search results. The contents and figures are based on [1].

38th International Cosmic Ray Conference (ICRC2023)
26 July - 3 August, 2023
Nagoya, Japan

ICRC2023
38th International Cosmic Ray Conference
The Astroparticle Physics Conference

*Speaker

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1. Introduction

Three gravitational wave (GW) observing runs have successfully completed by Advanced LIGO and Advanced Virgo [2]. During these runs, 90 GW events originated from compact binary coalescences were detected. On May 24, 2023, the fourth observing run has started. As of the time of this presentation, about 20 significant detection candidates were reported[1].

KAGRA [3], the fourth km-scale detector, was also planning to join the third observing run (O3) with LIGO and Virgo detectors. KAGRA achieved the binary neutron stars (BNS) observable range of 1 Mpc in March 2020. This sensitivity was threshold to join the observing run as a member of the GW detector network. However, due to the COVID-19 pandemic, the LIGO and Virgo detectors terminated the operations in March 2020, which was one month earlier than the planned end of the O3 period. Fortunately, the GEO 600 (hereafter GEO)[4–6] detector was still in the operation, therefore, KAGRA started the observation with GEO, which is called O3GK run.

KAGRA took the scientific data from April 7 to 20, 2020 and the data were analyzed to search for GW signals with the GEO data. We perform two all sky searches: one is a search for the BNS signals and the other is a search for generic short transient (burst) signals. In addition, we also perform two searches for GW signals associated with gamma-ray bursts (GRB) events observed during the run. In this proceeding, we briefly summarize the search results from KAGRA's first observation.

2. Detector properties

In this section, we show the representative detector sensitivities during the run in Fig. 1. Left panel shows the amplitude spectral density for GEO and KAGRA, and the right panel shows the time evolution of the sensitivity as the observable BNS ranges.

During two weeks of the observation, the duty cycles were 79.8 % for GEO and 53.5 % for KAGRA. The coincident duty cycle was 46.8 %.

In both detectors, there were many transient noise fluctuations. During the run, median rates of such noise identified by Omicron [7] with signal-to-noise ratio (SNR) larger than 6.5 were 10.3 per minute for GEO and 6.8 per minute for KAGRA. More detail properties of the KAGRA detector during the run are summarized in [8].

3. All-sky searches

In this section, we show the results from the all-sky search. All-sky search means that we analyze all of the data assuming that signals are arriving from any direction at any time.

3.1 Search for binary neutron stars

We first show the results of the search for BNS signals using the GstLAL library [9–11]. GstLAL performs a matched filter for various template waveforms with the component masses from 1 $M_\odot$ to 3 $M_\odot$. TaylorF2 [12] and SEOBNRv4 [13] are used for template waveforms depend

[1] https://gracedb.ligo.org/superevents/public/O4/

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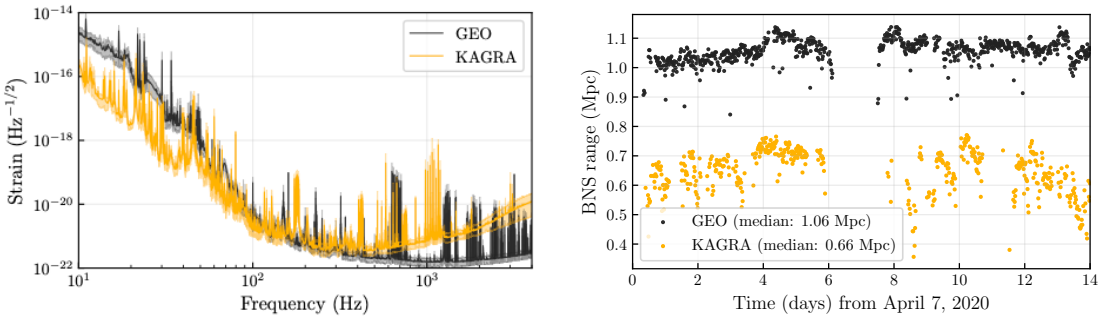

Figure 1: Left panel: The amplitude spectral density for GEO and KAGRA. The solid curves show the mean sensitivity for each frequency bin and the shaded regions show the 5th and 95th percentile over the period. Right panel: The time evolution of the BNS inspiral ranges for GEO and KAGRA. Both figures are from [1].

on the mass range. GstLAL defines triggers when the maximum of SNR in 1 s window is larger than 4 in at least one detector.

Both non-coincident triggers and coincident triggers form the event candidates. Each candidate is represented by a vector of parameters describing both its own characteristics and the characteristics of the detectors at the time it was observed. Candidates are ranked by the log-likelihood ratio for that vector; candidates for which the network SNR is below 7 are vetoed. The distribution function for the log-likelihood ratios due to the noise process is estimated from the Monte Carlo techniques. The total amount of the data are 11.70 days (0.032 years) including GEO-only, KAGRA-only, and coincident time. The number of candidate events is plotted as a function of inverse false alarm rate (iFAR) in the left panel of Fig. 2. The most significant candidate was found as a coincident trigger at April 20, 2020 14:03:28 UTC with FAR of $\sim$ 30 per year. This is consistent with the predicted noise distribution within the error.

By injecting simulated signals into the data, we can measure the search sensitivity as the sensitive spacetime volume. We inject many simulated BNS signals with mean component mass $1.4M_{\odot}$ and a standard deviation of $0.01M_{\odot}$. Their sources are uniformly distributed between 0.1 Mpc and 3 Mpc, and isotropically across the sky and in orientation. By converting the sensitivity volume to the equivalent sensitive range, the most significant candidate corresponds to a range of $\sim$ 0.6 Mpc, which agrees with the average detector sensitivity of KAGRA during the run shown in Fig. 1.

3.2 Search for transient signals

Next, we show the results of the search for unmodelled transient signals using the coherent WaveBurst (cWB) pipeline [14, 15]. This pipeline searches for coincident excess signal power in a network of GW detectors for the frequency range of 64–1024 Hz. Candidate events are ranked by their coherent network SNR, where the threshold of 5 is applied. The total coincident time was 4.38 days (0.012 years). The pipeline estimates the background event distribution by artificially time-shifting the data from one detector with respect to the other. For this search, a background livetime of 7.2 years was obtained. The background distribution and the candidate event are shown

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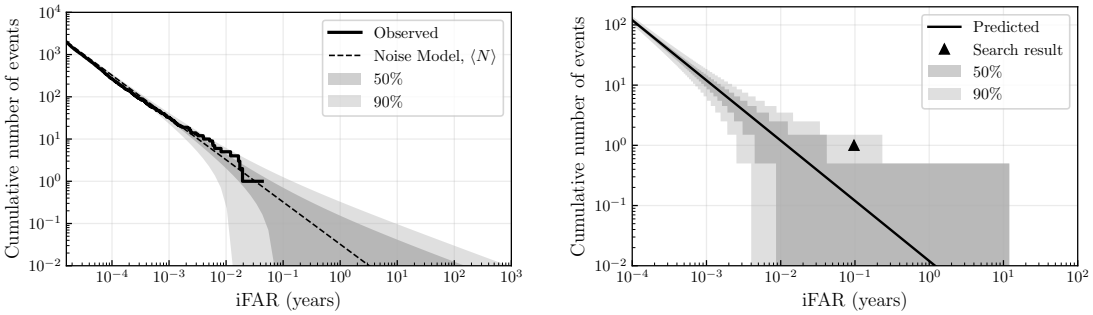

Figure 2: Left panel: The number of events as a function of iFAR for the BNS search by GstLAL. The solid line is obtained from the data and the the dashed line is the predicted distribution due to noise. The shaded region corresponds to the 50% and 90% error regions. Right panel: Background event distribution (solid line) and the candidate event (triangle) as a function of iFAR obtained by the cWB search. The shaded region corresponds to the 50% and 90% error regions. Both figures are from [1]

in the right panel of Fig. 2. The candidate event was identified at April 12 2020 18:10:15 UTC with an FAR of ~ 10 per year, which is consistent with the noise background within the error.

We also estimate the search sensitivity by injecting various types of burst signals and astrophysical signals. For GW150914-like signals, the distance of 50% detection efficiency at FAR of one per year is ~ 800 kpc. For a supernova-like signal, it is 80 kpc for 50% detection efficiency and 10 kpc for 90% detection efficiency.

4. Gamma-ray bursts targeted search

In this section, we show the results from searches for GW signals associated with GRBs. Four GRBs were observed during the run when both detectors were operating: GRB 200412A, GRB 200415A, GRB 200418A, and GRB 200420A. Among four GRB events, GRB 200415A is thought to be a magnetar giant flare in the nearby galaxy NGC 253 at 3.5 Mpc.

4.1 Search for compact binary coalescences

Since short GRBs are thought to be produced by neutron star binary mergers, we search for BNS or neutron star-black hole binary (NSBH) signals for two short GRBs (GRB 200415A and GRB 200420A) by using the PyGRB library [16]. The search performs a matched filter coherently across the operational detector network from -5 seconds to $+1$ second around the time of each GRB (on-source) with specific sky positions identified by GRB events. To estimate the background distribution, ~ 90 min of data surrounding the on-source time are used (off-source). Similar to the cWB search, the time shifting is applied to the off-source data to enhance the effective observing time. Then, the same analysis is done to the off-source data. IMRPhenomD [17, 18] is used as a template for this analysis. The p-values for the loudest candidates were 0.43 and 0.45 for GRB 200415A and GRB 200420A, respectively. They are consistent with the background noise.

By injecting simulated signals to the off-source data, we estimate the exclusion distances. A 90% exclusion distance means that we can recover 90% of a population of simulated signals as large as the loudest on-source candidate at the distance. The exclusion distances for GRB 200415A is

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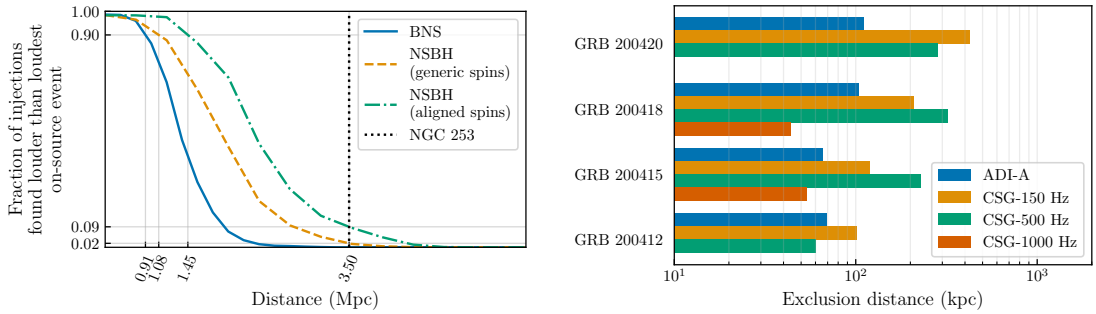

Figure 3: Left panel: Exclusion distance for GRB 200415A obtained by PyGRB for three different compact binary models. Right panel: Exclusion distances for four GRBs obtained by X-pipeline assuming different transient signals. Both figures are from [1]

shown in the left panel of Fig. 3 for three compact binary models. The largest 90% exclusion distance was 1.45 Mpc given by aligned spin NSBH model, which is less than the distance of NGC 253. Therefore, we cannot confidently exclude any binary merger as the progenitor of GRB 200415A. For GRB 200420A, the largest 90% exclusion distance was 0.21 Mpc given by isotropically spinning NSBH model.

4.2 Search for transient signals

We also search for transient signals around the time for four GRBs by using X-pipeline [19]. X-pipeline searches excess signal power coherently across the detector network with specific sky location (with errors) and the time window identified by the GRB detections for each GRB . The search is done for the frequency range of 30–1100 Hz. For the on-source data, the period from −600 seconds to +60 second around the time of each GRB is used[2]. For the off-source data, the period of ±90 min around the GRB event is used and time shifting is also applied for the background estimation to achieve p-values of order of 10^{-4}. The lowest p-value was 0.132 for GRB 200420A, which is consistent with the null hypothesis.

Exclusion distances are estimated by injecting burst signals with several central frequencies and the signal modeled by the accretion disk instability (ADI) for four GRBs as shown in the right panel of Fig. 3. The 90% exclusion distances were from O(10 kpc) to O(100 kpc) for all GRB events.

5. Summary

KAGRA conducted its first joint observation with GEO 600 for two weeks from April 7 to 20 2020. We perform two all sky searches and two searches dedicated to gravitational wave signals associated with gamma-ray burst events observed during the run. All of four pipelines are standard ones already used in the analysis of the LIGO and Virgo data. We have not found any significant GW signals from four searches, which was expected from the sensitivity of KAGRA and GEO at

[2]For GRB 200415A, the data from −519 seconds to +60 seconds are used.

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that time. However, we have shown that these pipelines worked well for the KAGRA data, which was an important milestone for KAGRA to become a member of the GW detector network.

All data used in the analyses are available through the Gravitational Wave Open Science Center [20].

Acknowledgments

This material is based upon work supported by NSF's LIGO Laboratory which is a major facility fully funded by the National Science Foundation. The authors also gratefully acknowledge the support of the Science and Technology Facilities Council (STFC) of the United Kingdom, the Max-Planck-Society (MPS), and the State of Niedersachsen/Germany for support of the construction of Advanced LIGO and construction and operation of the GEO 600 detector. Additional support for Advanced LIGO was provided by the Australian Research Council. The authors gratefully acknowledge the Italian Istituto Nazionale di Fisica Nucleare (INFN), the French Centre National de la Recherche Scientifique (CNRS) and the Netherlands Organization for Scientific Research (NWO), for the construction and operation of the Virgo detector and the creation and support of the EGO consortium. The authors also gratefully acknowledge research support from these agencies as well as by the Council of Scientific and Industrial Research of India, the Department of Science and Technology, India, the Science & Engineering Research Board (SERB), India, the Ministry of Human Resource Development, India, the Spanish Agencia Estatal de Investigación (AEI), the Spanish Ministerio de Ciencia e Innovación and Ministerio de Universidades, the Conselleria de Fons Europeus, Universitat i Cultura and the Direcció General de Política Universitaria i Recerca del Govern de les Illes Balears, the Conselleria d'Innovació, Universitats, Ciència i Societat Digital de la Generalitat Valenciana and the CERCA Programme Generalitat de Catalunya, Spain, the National Science Centre of Poland and the European Union – European Regional Development Fund; Foundation for Polish Science (FNP), the Swiss National Science Foundation (SNSF), the Russian Foundation for Basic Research, the Russian Science Foundation, the European Commission, the European Social Funds (ESF), the European Regional Development Funds (ERDF), the Royal Society, the Scottish Funding Council, the Scottish Universities Physics Alliance, the Hungarian Scientific Research Fund (OTKA), the French Lyon Institute of Origins (LIO), the Belgian Fonds de la Recherche Scientifique (FRS-FNRS), Actions de Recherche Concertées (ARC) and Fonds Wetenschappelijk Onderzoek – Vlaanderen (FWO), Belgium, the Paris Île-de-France Region, the National Research, Development and Innovation Office Hungary (NKFIH), the National Research Foundation of Korea, the Natural Science and Engineering Research Council Canada, Canadian Foundation for Innovation (CFI), the Brazilian Ministry of Science, Technology, and Innovations, the International Center for Theoretical Physics South American Institute for Fundamental Research (ICTP-SAIFR), the Research Grants Council of Hong Kong, the National Natural Science Foundation of China (NSFC), the Leverhulme Trust, the Research Corporation, the Ministry of Science and Technology (MOST), Taiwan, the United States Department of Energy, and the Kavli Foundation. The authors gratefully acknowledge the support of the NSF, STFC, INFN and CNRS for provision of computational resources. This work was supported by MEXT, JSPS Leading-edge Research Infrastructure Program, JSPS Grant-in-Aid for Specially Promoted Research 26000005, JSPS Grant-in-Aid for Scientific Research on Innovative Areas 2905: JP17H06358, JP17H06361

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and JP17H06364, JSPS Core-to-Core Program A. Advanced Research Networks, JSPS Grant-in-Aid for Scientific Research (S) 17H06133 and 20H05639 , JSPS Grant-in-Aid for Transformative Research Areas (A) 20A203: JP20H05854, the joint research program of the Institute for Cosmic Ray Research, University of Tokyo, National Research Foundation (NRF), Computing Infrastructure Project of KISTI-GSDC, Korea Astronomy and Space Science Institute (KASI), and Ministry of Science and ICT (MSIT) in Korea, Academia Sinica (AS), AS Grid Center (ASGC) and the Ministry of Science and Technology (MoST) in Taiwan under grants including AS-CDA-105-M06, Advanced Technology Center (ATC) of NAOJ, and Mechanical Engineering Center of KEK.

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