



Complexity of Magnetic-field Turbulence at Reconnection Exhausts in the Solar Wind at 1 au

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Abstract

Magnetic reconnection is a complex mechanism that converts magnetic energy into particle kinetic energy and plasma thermal energy in space and astrophysical plasmas. In addition, magnetic reconnection and turbulence appear to be intimately related in plasmas. We analyze the magnetic-field turbulence at the exhaust of four reconnection events detected in the solar wind using the Jensen–Shannon complexity-entropy index. The interplanetary magnetic field is decomposed into the LMN coordinates using the hybrid minimum variance technique. The first event is characterized by an extended exhaust period that allows us to obtain the scaling exponents of higher-order structure functions of magnetic-field fluctuations. By computing the complexity-entropy index we demonstrate that a higher degree of intermittency is related to lower entropy and higher complexity in the inertial subrange. We also compute the complexity-entropy index of three other reconnection exhaust events. For all four events, the B_L component of the magnetic field displays a lower degree of entropy and higher degree of complexity than the B_M and B_N components. Our results show that coherent structures can be responsible for decreasing entropy and increasing complexity within reconnection exhausts in magnetic-field turbulence.

Unified Astronomy Thesaurus concepts: [Interplanetary turbulence \(830\)](#); [Space plasmas \(1544\)](#); [Solar wind \(1534\)](#)

1. Introduction

Magnetic reconnection in plasmas refers to the process in which magnetic energy is converted to particle kinetic and thermal energy, resulting in a change of topology of the magnetic-field lines (Yamada et al. 2010; Treumann & Baumjohann 2013; Lazarian et al. 2015). The study of magnetic reconnection is key to understand the dynamics of solar flares, coronal mass ejections, rope-rope magnetic reconnection in the solar wind, and the interaction between solar wind and planetary magnetospheres. In addition, magnetic reconnection, turbulence, and intermittency seem to be intrinsically related in plasmas in a complex manner; hence, they need to be studied in relation to each other.

The solar wind is a natural laboratory for the study of magnetic reconnection. The conversion of magnetic energy into particle kinetic energy during the reconnection process leads to the formation of magnetic exhausts. The properties of magnetic exhausts have been studied recently using observational data. For example, Enžl et al. (2014) performed a statistical survey of 418 reconnection exhausts detected by the Wind spacecraft. They showed that the magnetic flux available for reconnection and the reconnection efficiency increase with the magnetic shear angle. Mistry et al. (2015) analyzed data from different spacecraft sampling oppositely directed reconnection exhausts of three different reconnection events. They showed that bifurcated current sheets are clearly observed when the spacecraft is located at a distance greater than $\sim 1000d_i$ from the X-line, where d_i is the ion skin depth. Chian et al. (2016) demonstrated that magnetic reconnection at the interface of two magnetic flux ropes provides an origin of intermittent magnetic-field turbulence in the solar wind. The statistics of 188 reconnection exhausts was studied by

Mistry et al. (2017). They showed that the guide magnetic field within the exhaust is enhanced, and the plasma density and ion temperature at the exhaust increase as a function of the inflow plasma beta and the guide field. Numerical simulations have also been used to understand the properties of the turbulent plasma in reconnection exhausts. Pucci et al. (2017) performed three-dimensional (3D) particle-in-cell (PIC) simulations of magnetic reconnection, and showed that the turbulence at the outflows is anisotropic, and that the energy exchange and dissipation is concentrated at the interface between the ejected plasma and the ambient plasma. The outflow region has also been identified by Lapenta et al. (2018) as a source of instabilities that feeds a turbulent cascade and secondary reconnection sites in 3D PIC simulations of reconnection with a weak guide field. Adhikari et al. (2020) computed the scaling laws of energy spectra and second-order structure functions of 2.5D PIC simulations. They demonstrated that the inflow region displays a lower degree of turbulence compared to the diffusion, exhaust, separatrix, and island regions resulting from the reconnection process. Hence, there is a need to quantitatively characterize the turbulent behavior in these regions (for example, using a complex system approach), which can complement theoretical and simulation efforts.

In this respect, the Jensen–Shannon (J–S) complexity-entropy index is a statistical tool that allows to distinguish noise from chaos (Rosso et al. 2007). It has been successfully applied to data from experiments with electronic oscillators (Soriano et al. 2011), stock market data (Zunino et al. 2009), the Southern Oscillation index (Bandt 2005), and heart rate variability (Bian et al. 2012), among others. For a detailed list of applications see Riedl et al. (2013). Weck et al. (2015) computed the J–S index of the interplanetary magnetic-field

Table 1
Time Interval and Number of Data Points of Four Magnetic Reconnection Exhaust Events

Event	Interval Start (UT)	Interval End (UT)	No. Data Points
1	30-12-1997 17:15:16	30-12-1997 17:38:02	14783
2	14-11-1998 07:53:09	14-11-1998 08:12:10	11936
3	23-11-1997 12:52:22	23-11-1997 13:07:28	8834
4	02-02-2002 02:32:05	02-02-2002 02:34:34	3333

data detected by the Wind spacecraft, magnetic-field data of the Swarthmore Spheromak Experiment (SSX), and the ion saturation current data at the edge of the Large Plasma Device (LAPD). They showed that the Wind data displays high entropy and low complexity, similar to stochastic signals; whereas the SSX and the LAPD data display intermediate entropy and high complexity, due to the lower number of degrees of freedom of the experimental devices and the confined nature of the experiments compared to the interplanetary magnetic-field data. The J-S index was also applied to solar wind data collected by the Helios, Wind, and Ulysses spacecraft by Weygand & Kivelson (2019). Several intervals were selected, including slow and fast solar wind, interplanetary coronal mass ejections, and corotating interactions regions. They also obtained J-S index values characteristic of stochastic fluctuations, and showed that the complexity decreases and the entropy increases with the distance from the Sun.

In this paper we characterize the complexity-entropy of magnetic-field data of four reconnection exhausts detected in the solar wind. For the first event, we show that intermittency and multifractality are related to the degree of entropy and complexity. By projecting the magnetic field into the LMN coordinates (Sonnerup & Cahill 1967; Gosling & Phan 2013), we show that the L component displays lower entropy and higher complexity than the M and N components. Our paper is organized as follows. Section 2 describes briefly the four magnetic reconnection events. Section 3 presents the methods employed for the data analysis. The results are presented in Section 4, and a discussion and conclusions are given in Section 5.

2. Magnetic Reconnection Events

We analyze four reconnection exhausts detected at 1 au. The timing of each interval is indicated in Table 1. Events 1 and 3 are magnetic reconnection exhausts detected by Wind at the interior of a magnetic cloud associated with an ICME, with a main shock arrival observed at 1:13 UT on 1997 December 30 and at 8:55 UT on 1997 November 22, respectively. Event 2 is a magnetic reconnection exhaust detected by Wind after the passage of an ICME with a main shock arrival observed at 7:18 UT on 1998 November 12. Event 4 is a reconnection exhaust detected by Cluster on 2002 February 2 (Phan et al. 2006). This exhaust is the result of the magnetic reconnection between a small-scale interplanetary magnetic flux rope (IMFR) and an intermediate-scale IMFR (Chian et al. 2016). We use the magnetic-field data from Wind at a resolution of 11 Hz for events 1, 2, and 3; whereas for event 4 we employ the data from Cluster at a resolution of 22 Hz.

The timing of events 1, 2, and 3 is based on the supplement table of 188 magnetic reconnection exhausts studied by Mistry et al. (2017). These events are the longest exhaust intervals during which the IMF experiment onboard Wind was operating

at 11 Hz, resulting in a sufficient number of data points for analysis. For event 4, we use the data from four Cluster spacecraft and apply the curlometer technique to compute the modulus of the current density \mathbf{J} . Since the exhaust is bounded by a bifurcated current sheet in the Petschek model of magnetic reconnection (Gosling & Szabo 2008), the exhaust interval of event 4 is defined using the timing of the main peaks of $|\mathbf{J}|$. Table 1 also indicates the number of data points available from each interval.

3. Methods

The vector magnetic field is projected on the LMN coordinate system by applying the hybrid minimum variance analysis (MVA; Gosling & Phan 2013; Mistry et al. 2015, 2017; Hietala et al. 2018). The L component is given by the direction of maximum variance and is related to the exhaust outflow direction, the M direction is related to the reconnection guide field direction, and the N component is the direction of minimum variance related to the normal of the current sheet. The N direction can be obtained as

$$\hat{e}_N = \frac{\mathbf{B}_1 \times \mathbf{B}_2}{|\mathbf{B}_1 \times \mathbf{B}_2|},$$

where \mathbf{B}_1 and \mathbf{B}_2 are the magnetic-field vectors immediately adjacent to the exhaust boundaries. The M direction is given by

$$\hat{e}_M = \hat{e}_N \times \hat{e}_{L'}, \quad (1)$$

where $\hat{e}_{L'}$ is the maximum variance direction obtained from the classical MVA (Sonnerup & Cahill 1967), and the L direction is

$$\hat{e}_L = \hat{e}_M \times \hat{e}_N. \quad (2)$$

Note that, from Equation (1), \hat{e}_N and $\hat{e}_{L'}$ are not necessarily orthogonal, whereas \hat{e}_N and \hat{e}_M are orthogonal. From Equation (2), \hat{e}_L is made orthogonal to \hat{e}_N and \hat{e}_M . The hybrid MVA is more reliable than the MVA (Knetter et al. 2004) because the MVA can fail to separate the intermediate and minimum variance directions properly, giving unrealistic values for the N component (Mistry et al. 2017).

We compute the power spectral density (PSD) of the B_L , B_M , and B_N components using the Welch method (Welch 1967), which allows us to reduce the error of the spectrum estimate. The compensated PSD is obtained by multiplying the original PSD by $f^{+5/3}$. The inertial subrange can be identified as a frequency range in which the compensated PSD is nearly horizontal.

The large number of data points within the exhaust interval of event 1 allows us to compute higher p th-order structure functions $S_p(\tau) = \langle |B_i(t + \tau) - B_i(t)|^p \rangle$, for $i = L, M, N$ (De Wit 2004; Miranda et al. 2013). The scaling exponents of structure functions can be computed from $S_p(\tau) \sim \tau^{\alpha(p)}$, to quantify the departure from self-similarity (i.e., multifractality). The scaling exponents $\alpha(p)$ can be obtained by plotting $S_p(\tau)$ as a function of τ in log-log scale, and applying a linear fit within the inertial subrange. The inertial subrange is identified as the range of scales in which $\alpha(p=3) = 1$. However, the number of scales within the inertial subrange can be small and difficult to determine, especially for short time series. Therefore, the numerical values of $\alpha(p)$ will be affected by a large statistical error. For this reason we apply the extended self-similarity (ESS) (Benzi et al. 1993) by assuming $S_p(\tau) \sim [S_3(\tau)]^{\zeta(p)}$, where $\zeta(p) \sim \alpha(p)/\alpha(3)$. The value of $\zeta(p)$ can be estimated by

plotting $S_p(\tau)$ as a function of $S_3(p)$ in log-log scale. The ESS technique results in a larger range of scales in which $\zeta(p=3) = 1$, thus reducing the statistical error and producing a more robust value for the computed scaling exponents.

We compute the J–S complexity index, in which a probability distribution function (PDF) of ordinal patterns is obtained from the magnetic-field data within the exhaust interval. This PDF represents the frequencies of occurrence of all possible ordinal patterns of length d (Bandt & Pompe 2002; Weck et al. 2015). For example, suppose that the time series of a component of the magnetic field starts with $\{-2.67, 10.80, 1.72, -2.40, 11.21, \dots\}$. The first d -tuple of length $d=3$ is $(-2.67, 10.80, 1.72)$ and the corresponding ordinal pattern, in ascending order, is $(1, 3, 2)$ because $-2.67 < 1.72 < 10.80$. The second 3-tuple is $(10.80, 1.72, -2.40)$ and the ordinal pattern is $(3, 2, 1)$. For a time series of length K , there are $K-d+1$ d -tuples and $d!$ possible permutations of a d -tuple. The PDF of ordinal patterns is obtained by counting the number of occurrences of each possible permutation of ordinal patterns within the time series

$$p_i = \frac{\#\{s \mid s \text{ is the } i\text{th ordinal pattern}\}}{K-d+1},$$

where “#” stands for “number”, and $K-d+1 > d!$. The Shannon entropy is given by

$$S(P) = -\sum_{i=1}^{d!} p_i \ln(p_i), \quad (3)$$

where P represents the PDF of ordinal patterns. The Shannon entropy is equal to zero if, for any i , $p_i=1$ and $p_j=0$, $j \neq i$. This case represents a completely ordered system. Conversely, the Shannon entropy will be maximum if all possible ordinal patterns have the same probability. In this case $S(P_e) = \ln(d!)$, where P_e represents the uniform distribution. The normalized Shannon entropy can be written as

$$H(P) = \frac{S(P)}{S(P_e)} = \frac{S(P)}{\ln(d!)}. \quad (4)$$

Similarly, the Jensen’s divergence measures the “disequilibrium”, or the “distance” between a distribution P and the uniform distribution P_e (Martin et al. 2006; Rosso et al. 2007)

$$Q_J(P, P_e) = Q_0 \left[S\left(\frac{P+P_e}{2}\right) - \frac{1}{2}S(P) - \frac{1}{2}S(P_e) \right], \quad (5)$$

where Q_0 is a normalization constant given by Martin et al. (2006)

$$Q_0 = -\frac{1}{2} \left[\frac{K+1}{K} \ln(K+1) - 2\ln(2K) + \ln(K) \right].$$

The J–S complexity is then given by

$$C_J^S = Q_J(P, P_e)H(P). \quad (6)$$

The pair (H, C_J^S) can be represented in a plane called the complexity-entropy (C-H) plane. This plane can be separated into three regions, namely, a low-entropy and low-complexity region corresponding to highly predictable systems, an intermediate-entropy and high-complexity region corresponding to unpredictable systems with a large degree of structure, and a high-entropy and low-complexity region corresponding to stochastic-like processes (Rosso et al. 2007).

The number of data points K needed to compute Equations (4) and (6) reliably is (Amigó et al. 2008; Riedl et al. 2013)

$$K > 5d!. \quad (7)$$

A large value of the d parameter can result in unreliable statistics, whereas a small value of d can result in an overestimated value of Equation (6) (Gekelman et al. 2014). We set d to the maximum value for which Equation (7) is satisfied for all intervals, as recommended by Amigó et al. (2008) and Riedl et al. (2013). For $d=5$ we need $K > 600$, whereas for $d=6$, $K > 3600$. From Table 1, all intervals have enough data points to satisfy Equation (7) with $d=5$.

4. Intermittency and Complexity in Reconnection Exhausts

We start our analysis by describing the solar wind conditions around event 1. Figure 1 shows an overview of the plasma parameters observed by the MFI and SWE instruments onboard Wind; namely, the modulus of the magnetic field $|\mathbf{B}|$ (nT): the three components of the magnetic field B_x , B_y , and B_z (nT) in the GSE coordinates; the modulus of the proton velocity $|V_p|$ (km s^{-1}); the proton density n_p (cm^{-3}); the proton temperature T_p (eV); and the proton beta $\beta_p = 8\pi n_p K_B T_p / |\mathbf{B}|^2$, where K_B is the Boltzmann constant. This event is characterized by a main shock arrival detected at 1:13 UT on 1997 December 30, and a magnetic cloud from 9:35 UT on December 30 to 8:51 UT on December 31 (Nieves-Chinchilla et al. 2018). This magnetic cloud is characterized by an increase on $|\mathbf{B}|$, a rotation of the magnetic-field direction, and a decrease in T_p and β_p . The horizontal lines indicate the boundaries of the ICME (black) and the magnetic cloud (violet), and the vertical dashed lines indicate the reconnection exhaust interval. Note that the value of β_p is low in Figure 1 outside the reconnection exhaust because this event occurs at the interior of a magnetic cloud.

Figure 2 shows a detailed view of the plasma parameters around event 1. The magnetic reconnection event is characterized by a decrease of $|\mathbf{B}|$, a change of the B_z magnetic-field component in the GSE coordinates, and an increase of the proton beta β_p . The magnetic-field components in the LMN coordinates are also shown. The reconnection event is also characterized by the corresponding increases of the V_z velocity component (in GSE), n_p , and T_p . The reconnection exhaust interval, bounded by the two vertical dashed lines, has a duration of 1343 seconds, which gives 14,783 data points within the exhaust (as indicated in Table 1).

The time series of the B_L component shown in Figure 2 displays discontinuous “jumps” near the boundaries of the reconnection exhaust interval, associated with the magnetic-field reversal that is required for the magnetic reconnection to occur. Since the magnetic shear occurs at a scale larger than the selected interval, we apply a trend removal technique to the time series of B_L . This is achieved by computing a third-order polynomial fit to the time series of B_L , and removing the resulting fit from the original time series. Figure 3(a) shows the time series of B_L after detrending, represented by B_L^* . We have also applied the same procedure to obtain the time series of the B_M^* and B_N^* components, shown in Figures 3(b) and 3(c), respectively. Hereafter, we will analyze the time series of B_L^* , B_M^* , and B_N^* , and refer them simply as B_L , B_M , and B_N , respectively.

Figure 4(a) shows the PSD of the B_L , B_M , and B_N components of the magnetic field. The dashed line in the

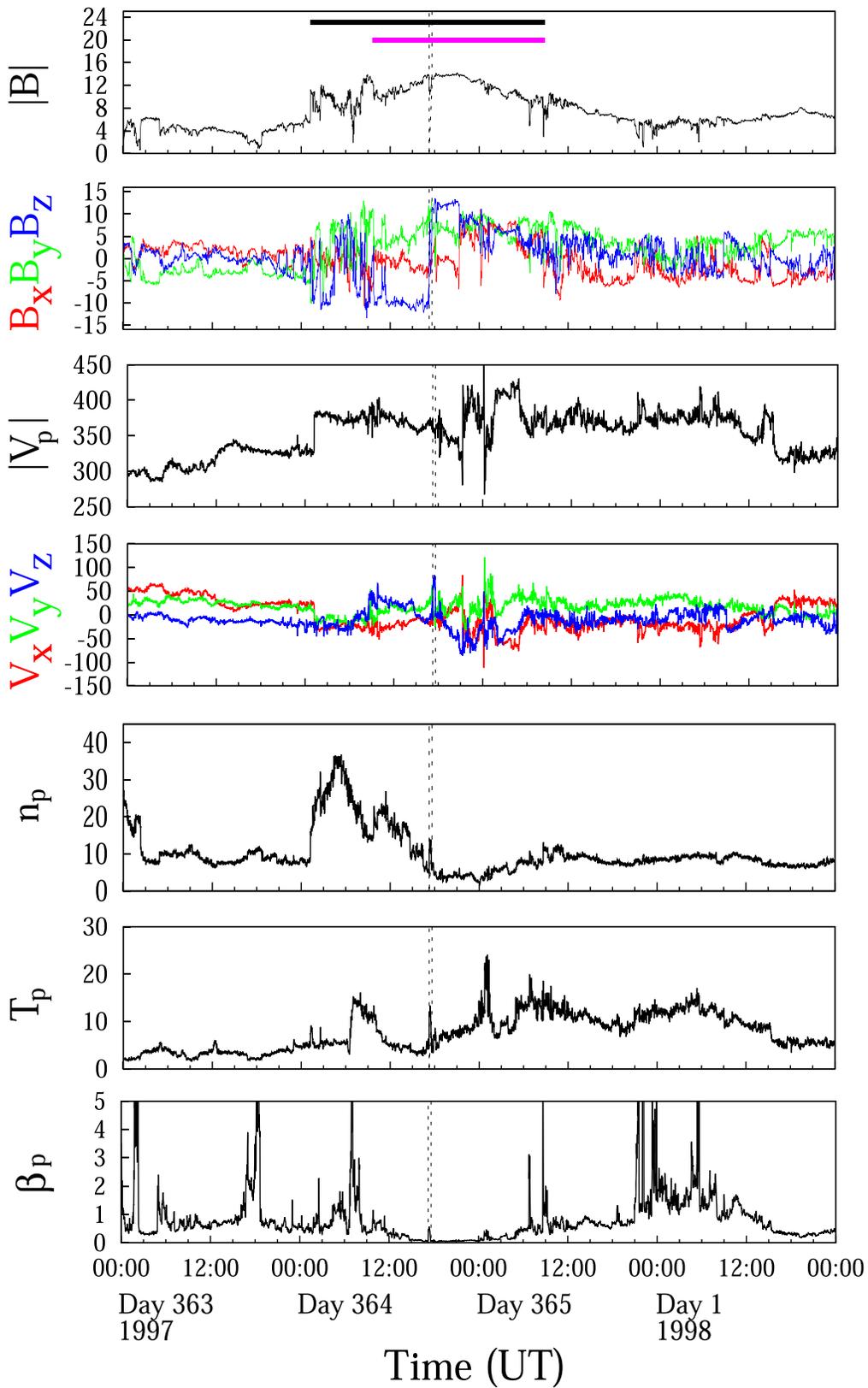


Figure 1. Interplanetary magnetic field and plasma data detected by the Wind spacecraft during the passage of an ICME on 1997 December 30 (Julian day 364). From top to bottom: the modulus of the magnetic field $|B|$ (nT); the three components of the magnetic field B_x , B_y , and B_z in GSE coordinates (nT); the modulus of the proton velocity $|V_p|$ (km s^{-1}); the three components of the proton velocity V_x , V_y , and V_z in GSE coordinates (km s^{-1}); the proton density n_p (cm^{-3}); the proton temperature T_p (eV); and the proton beta β_p . The horizontal black line in the top panel indicates the ICME interval, and the violet horizontal line indicates the magnetic cloud interval. The vertical dashed lines indicate the reconnection exhaust interval.

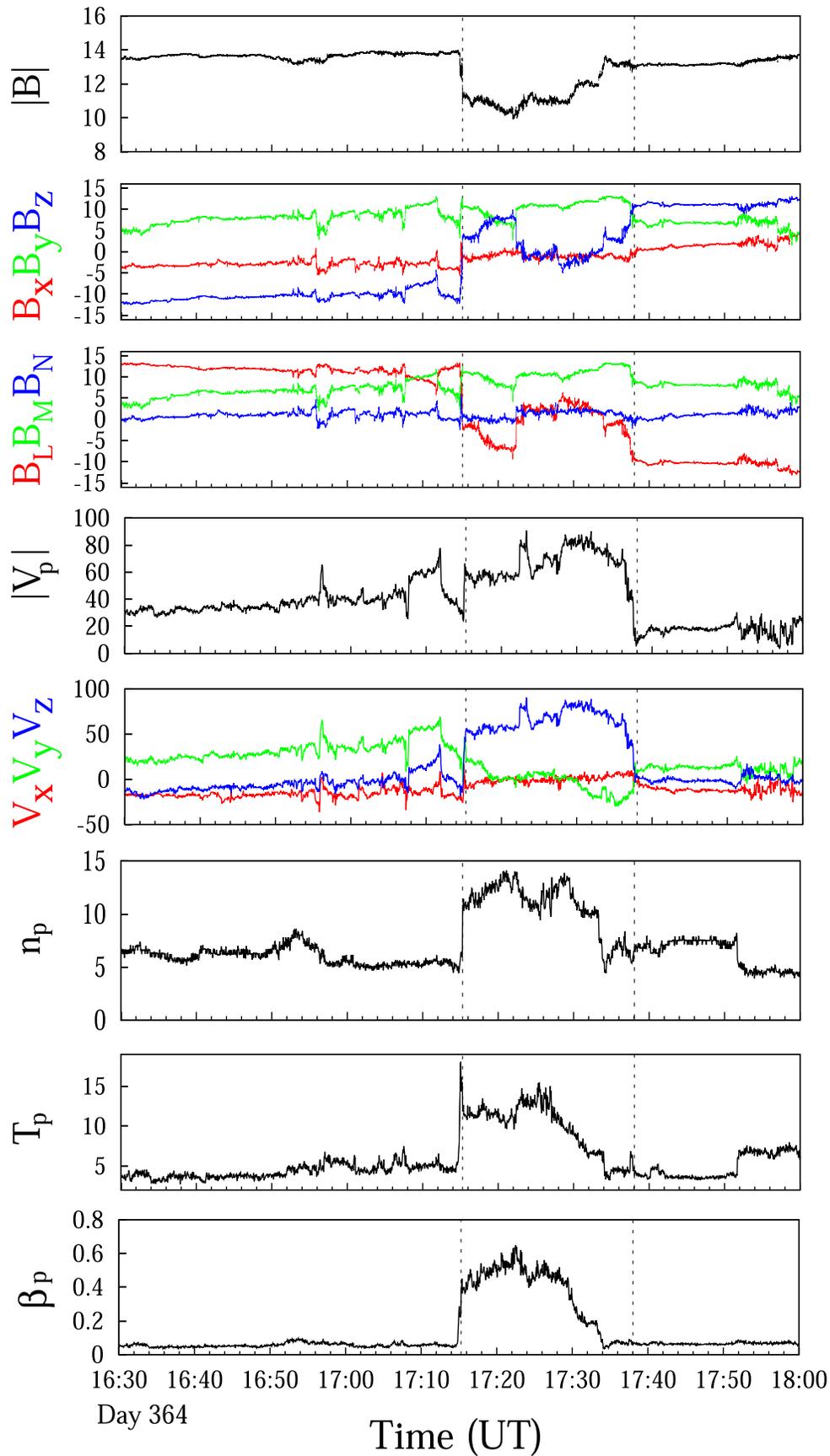


Figure 2. Magnetic reconnection exhaust (event 1) detected on 1997 December 30. From top to bottom: the modulus of the magnetic field $|\mathbf{B}|$ (nT); the three components of \mathbf{B} in the GSE coordinates (nT); the three components of \mathbf{B} in the LMN coordinates (nT); the modulus of the proton velocity $|\mathbf{V}_p|$ (km s^{-1}); the three components of \mathbf{V}_p in the GSE coordinates (km s^{-1}), where V_x has been shifted by $+350 \text{ km s}^{-1}$; the proton number density n_p (cm^{-3}); the proton temperature T_p (eV); and the proton beta β_p . The exhaust interval is bounded by the two vertical dashed lines, which define \mathbf{B}_1 and \mathbf{B}_2 , respectively.

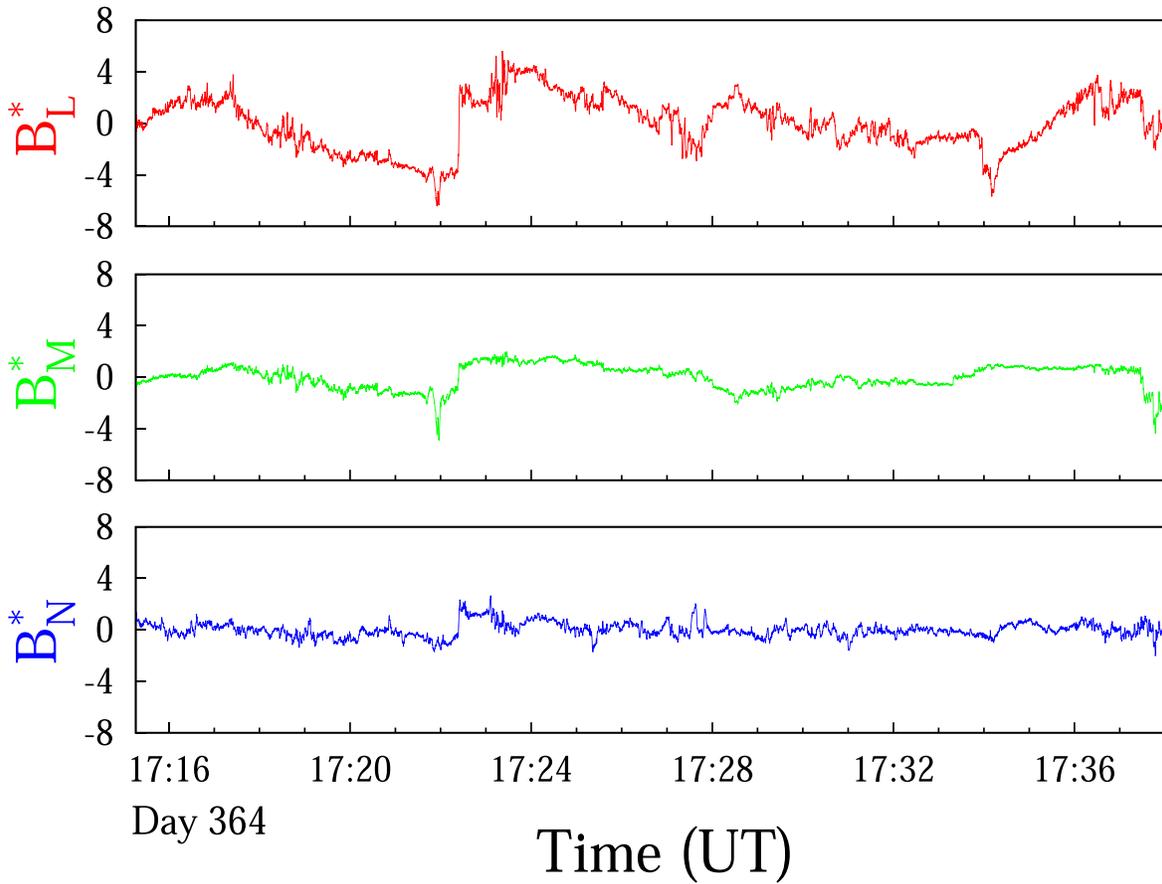


Figure 3. The time series of B_L^* , B_M^* , and B_N^* , obtained by removing the trend computed by applying a third-order polynomial fit to the original data (event 1).

upper panel indicates the $-5/3$ power-law scaling within the inertial subrange. This interval was obtained by plotting the compensated PSD shown in the lower panel of Figure 4(b). In this figure the range of scales in which the PSDs of B_L , B_M , and B_N are nearly horizontal is indicated by vertical dashed lines.

We compute the scaling exponents ζ of the structure functions with the ESS technique (i.e., $S_p(\tau) \sim [S_3(\tau)]^{\zeta(p)}$), within the inertial subrange identified by the compensated PSD. Figure 5 shows the structure functions before and after applying the ESS technique to the time series of the B_L component. The inertial subrange in Figure 5(a), shown as a gray background, is obtained from the compensated PSD of Figure 4(b), and coincides with the interval in which α ($p=3$) = 1. The gray background of Figure 5(b) indicates the extended interval in which the scaling exponents ζ are obtained. The horizontal black line represents the original inertial subrange. Note that the extended interval cannot include kinetic scales, which starts near the ion cyclotron frequency. From Figure 4, a spectral break marking the end of the inertial subrange occurs near $f=0.5$ Hz, which corresponds to a scale of $\tau \sim 2$ s. This scale is outside the shaded region of Figure 5(a), and corresponds to $S_3(\tau)/S_3(T) = 238$ in the horizontal axis of Figure 5(b), which is also outside the interval used to compute the scaling exponents. We have also applied the ESS technique to the structure functions of the B_M and B_N components using the same procedure.

Figure 6 shows ζ as a function of the p -th order structure function for B_L , B_M , and B_N . The vertical bars indicate the error in the fit. Intermittency and multifractality within the inertial subrange are responsible for deviations of ζ from the linear

scaling of Kolmogorov’s 1941 (hereafter K41) self-similar model. This figure shows clearly that, for higher-order statistics, the B_L component displays a stronger departure from the K41 scaling than B_M , which in turn displays a greater departure than B_N . Therefore, the B_L component displays a higher degree of multifractality and intermittency than the B_M and the B_N components.

Next, we show how the intermittency of the magnetic-field fluctuations is related to entropy and complexity for event 1. We compute the J–S index (i.e., Equations (4) and (6)) for B_L , B_M , and B_N . Figure 7 shows the $d=5$ C–H plane. The crescent-shaped curves indicate the minimum and maximum values of C_J^S for a given value of H . Symbols indicate the (H, C_J^S) values of three chaotic maps, namely, the logistic map $x_{n+1} = rx_n(1 - x_n)$ with $r=4$; the skew tent map

$$\begin{aligned} x/w, & \quad x \in [0, w], \\ (1-x)/(1-w), & \quad x \in [w, 1], \end{aligned}$$

with $w = 0.1847$; and the Hénon map

$$\begin{aligned} x_{n+1} &= 1 - ax_n^2 + y_n, \\ y_{n+1} &= bx_n, \end{aligned}$$

with $a = 1.4$ and $b = 0.3$. The parameter values of the chaotic maps are the same from Rosso et al. (2007) and Weck et al. (2015). Their locations on the C–H plane identify the region corresponding to deterministic chaotic behavior. The dotted curve represents the (H, C_J^S) values of stochastic fractional Brownian motion (fBm). This curve was computed by

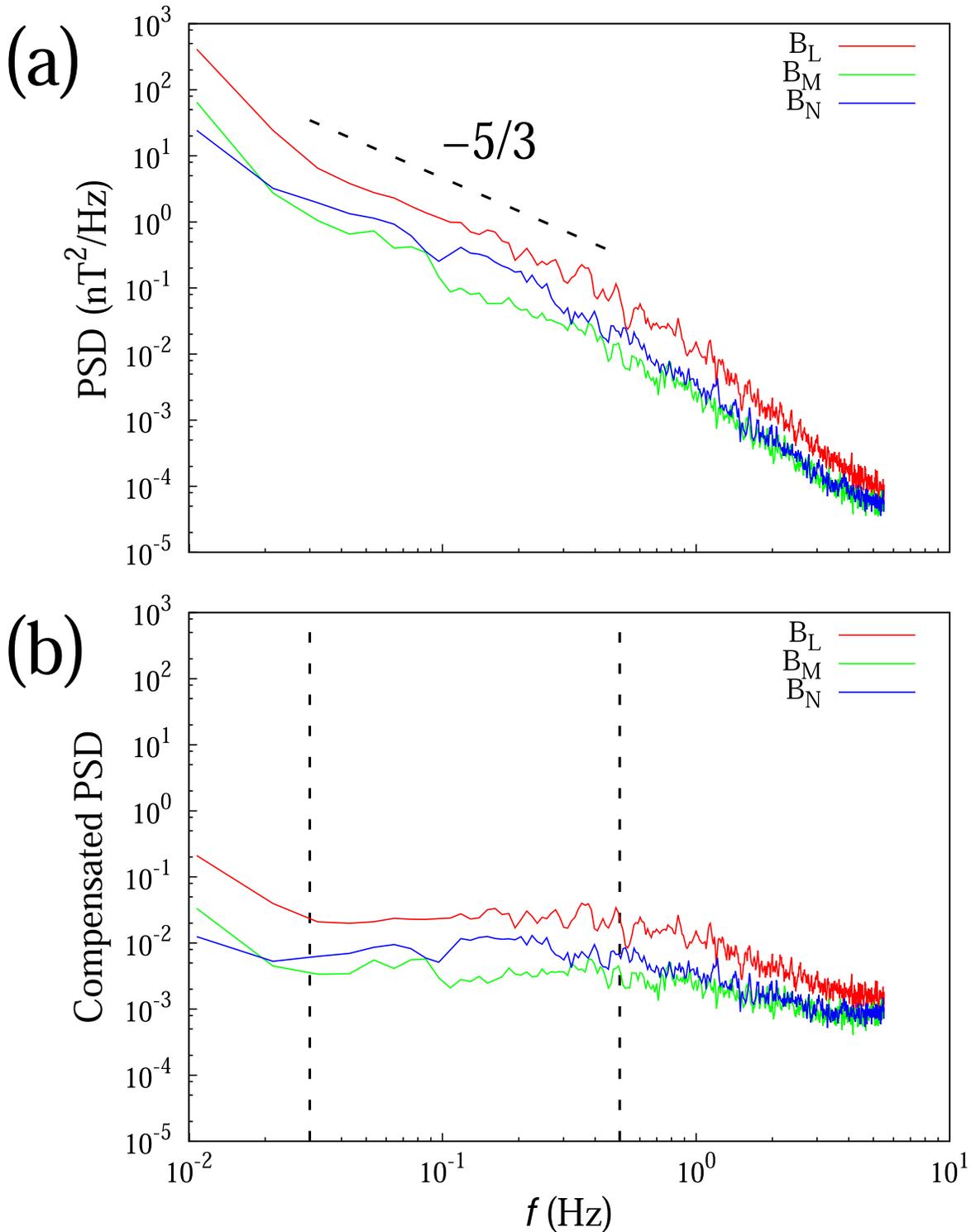


Figure 4. (a) PSD of the B_L , B_M , and B_N components of the magnetic field (event 1). (b) Compensated PSD. The dashed vertical lines indicate the inertial subrange in which the compensated PSD is nearly horizontal.

generating time series of fBm with a Hurst exponent varying within the interval $[0.025, 0.925]$ (Maggs & Morales 2013). Smaller Hurst exponents display larger H and lower C_J^S values. The chaotic maps and stochastic signals allow us to illustrate the different regions of the C-H plane.

The ordinal PDFs of B_L , B_M , and B_N are computed by setting the size of the ordinal pattern to $d=5$. We also define an

embedding delay T , which means that d -tuples are sampled on a larger timescale instead of consecutive points. This allows us to relate the computed (H, C_J^S) values to a given timescale. We set the embedding delay $T=110$ data points. For event 1, this value of T corresponds to a timescale of 10 s, which is within the inertial subrange (see Figure 4). Similar results were obtained for embedding delay values corresponding to

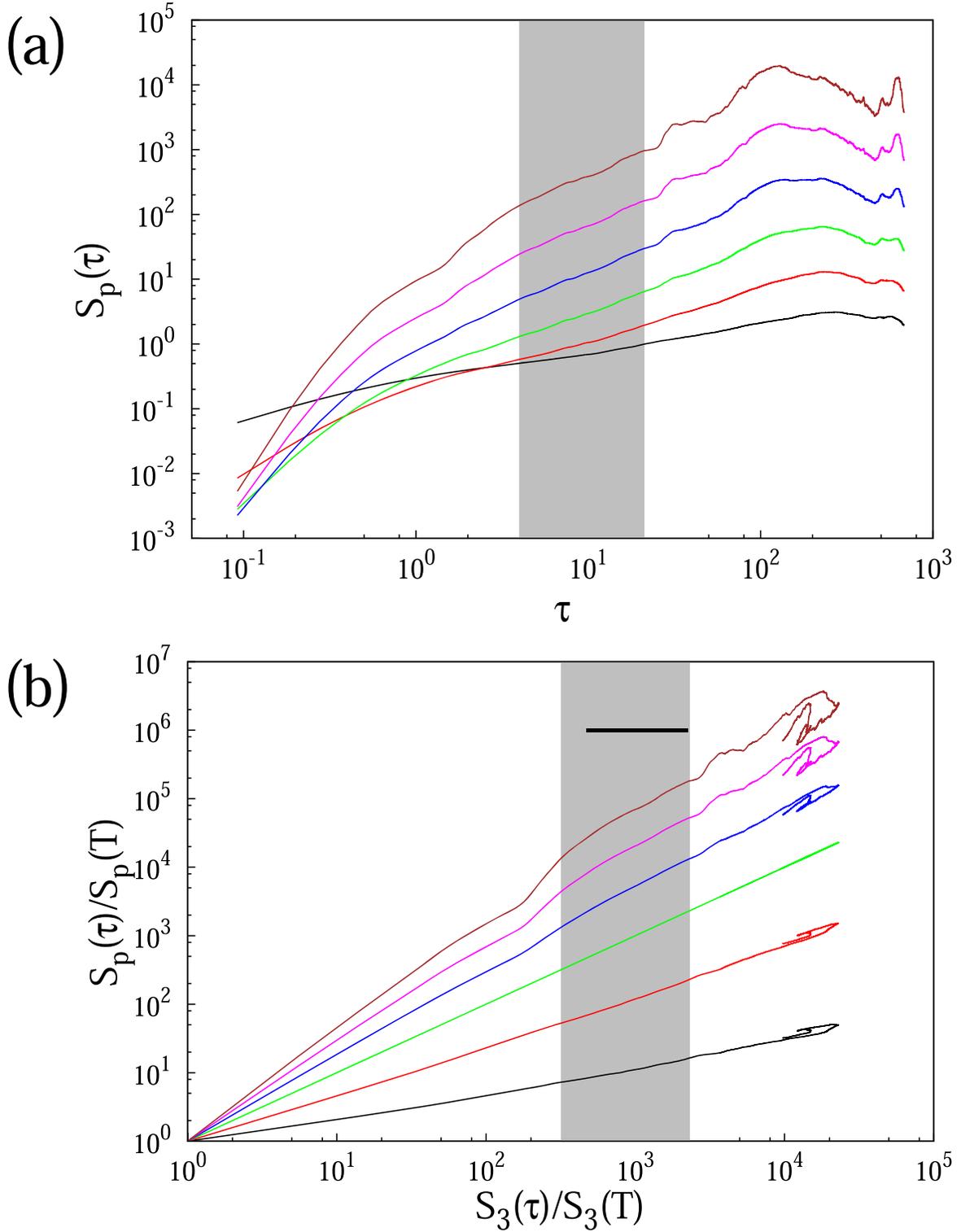


Figure 5. (a) Structure functions as a function of τ computed from the B_L component of the magnetic field (event 1), for $p = 1$ (black), $p = 2$ (red), $p = 3$ (green), $p = 4$ (blue), $p = 5$ (violet), and $p = 6$ (brown). The gray area represents the inertial subrange ($\tau \in [4, 21]$ s). (b) The structure functions after applying the extended self-similarity technique. The horizontal line represents the original inertial subrange, and the gray area represents the extended scaling range ($S_3(\tau)/S_3(T) \in [320, 2302]$). The structure functions have been normalized to $S_p(T = 0.091 \sim 1/11$ s). Note that the spectral break in Figure 4 occurs at scale $\tau \sim 2$ s, which corresponds to $S_3(\tau)/S_3(T) = 238$ in panel (b).

timescales $\in [5, 15]$ s. Figure 7 shows that the three magnetic-field components display (H, C_J^S) values close to the bottom-right region of the C-H plane, which correspond to stochastic-like processes. However, the B_L component displays a lower

degree of entropy and a higher degree of complexity than the B_M component, which in turn displays lower entropy and higher complexity than the B_N component. This pattern is also observed when we choose different values of d . Setting $d = 4$,

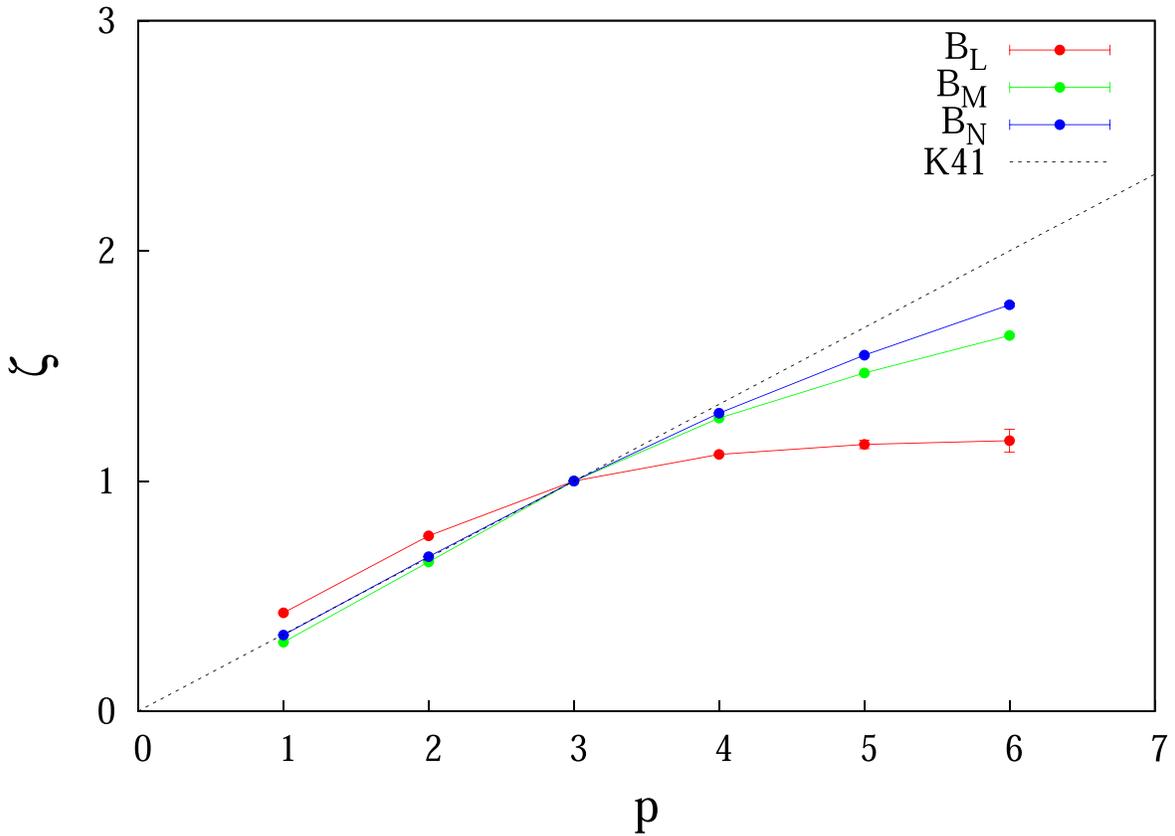


Figure 6. Scaling exponents for the B_L , B_M , and B_N components at the exhaust region (event 1). The dotted line represents the K41 monofractal scaling with $\zeta(p) = p/3$.

the (H, C_j^S) values of the three magnetic-field components are slightly shifted closer to the bottom-right region of the entropy-complexity plane, while their relative positions in the C-H plane with respect to each other are maintained. For $d=6$, the three values are slightly shifted away from this region, also keeping their relative positions in the C-H plane, demonstrating the robustness of this result. Note that the number of data points of event 1 still satisfy Equation (7) with $d=6$. The numerical values of (H, C_j^S) for $d=4, 5$, and 6 are given in Table 2.

We apply the same analysis to events 2, 3, and 4, except for the computation of scaling exponents, because the number of data points for each of these events is insufficient to guarantee the convergence of high-order statistics. However, as stated in Section 3, the number of data points of these events satisfy Equation (7) for $d=5$, allowing us to compute H and C_j^S . Figure 7 shows the entropy-complexity plane of the four reconnection exhausts. For all the analyzed events, the B_L component displays lower values of H and higher values of C_j^S , as compared with the B_M and B_N components.

5. Discussion and Conclusions

The results shown in Figures 6 and 7 suggest that a higher degree of intermittency is related to a decrease of entropy and an increase of complexity. Intermittency is related to the presence of coherent structures in turbulent fluids and plasmas, resulting in non-Gaussian PDFs (Sorriso-Valvo et al. 2001; Chian & Miranda 2009), a finite degree of amplitude-phase synchronization (Koga et al. 2007; Chian & Miranda 2009), and multifractal scaling exponents (Bershadskii & Sreenivasan 2004; Bruno et al. 2007; Miranda et al. 2013). Coherent

structures are also responsible for lower values of the Fourier power spectral entropy in 3D compressible MHD simulations of an intermittent dynamo (Rempel et al. 2009) and lower values of the spectral power and phase entropies in 3D incompressible MHD simulations of a Keplerian shear flow (Miranda et al. 2015). We have shown that the B_L , B_M , and B_N components have H and C_j^S values similar to stochastic fluctuations, in agreement with previous analyses of interplanetary magnetic-field data (Weck et al. 2015; Weygand & Kivelson 2019). Our results indicate that, within magnetic reconnection exhausts, coherent structures are responsible for decreasing entropy and increasing complexity. We note that the H and C_j^S values of the B_L , B_M , and B_N components are consistent with those of fBm with Hurst exponents 0.525, 0.425, and 0.335, respectively. These values can provide additional quantitative constraints to simulation and modeling of magnetic reconnection in plasmas.

By comparing the J-S index of the B_L , B_M , and the B_N magnetic-field components we have shown that, for the four events selected, the B_L component has lower entropy and higher complexity than the B_M component, and the B_M component has lower entropy and higher complexity than the B_N component. From the analysis of event 1 it follows that the B_L component is more intermittent than B_M and B_N due to coherent structures within the inertial subrange. Coherent structures and intermittency are also related to energy dissipation in anisotropic MHD turbulence (Müller et al. 2003; Miranda et al. 2013). Our results indicate that the energy dissipation in these four magnetic reconnection exhaust events is strongest in the B_L component. For events 2, 3, and 4, high-order statistics and scaling exponents cannot be computed

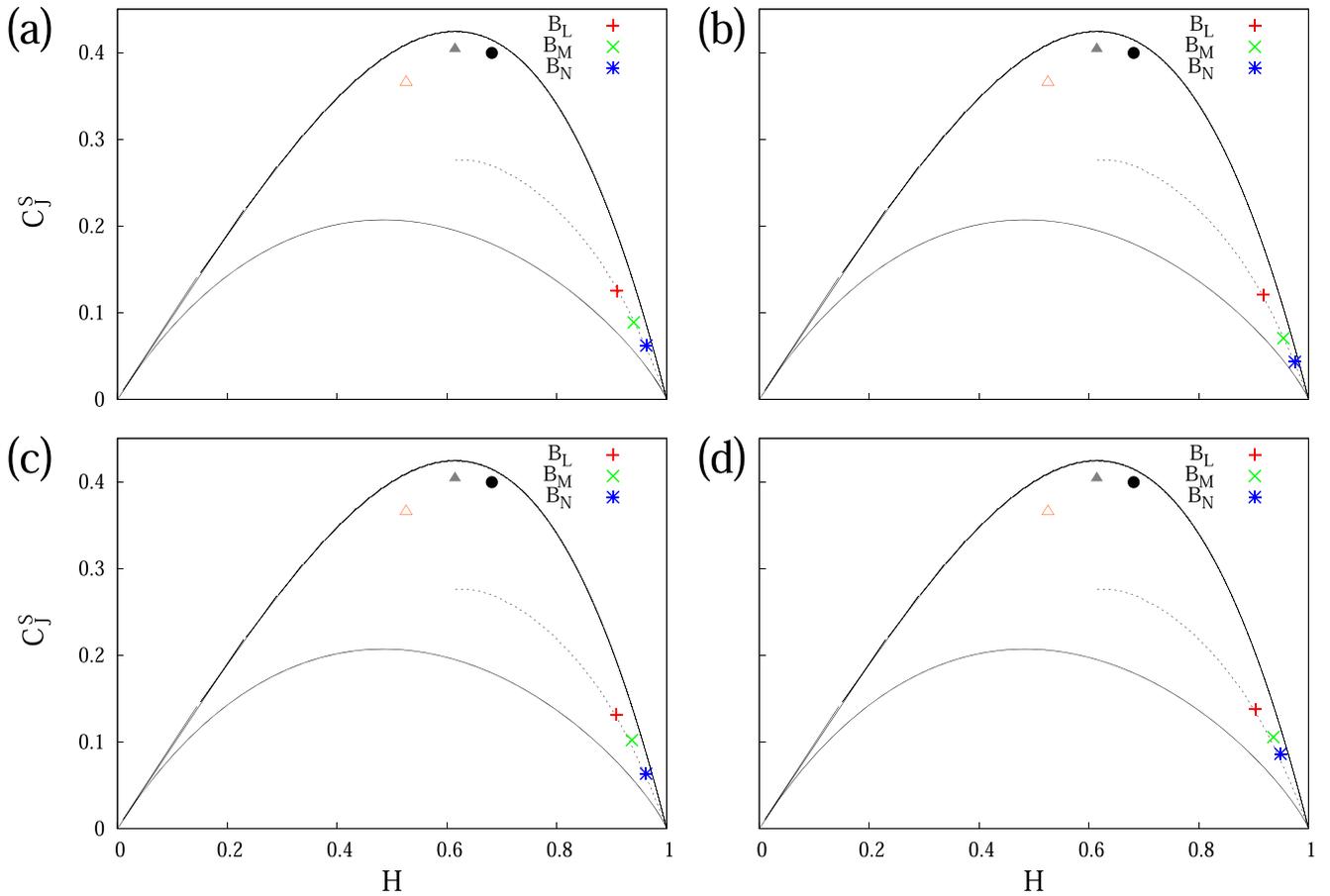


Figure 7. The $d = 5$ C-H plane for the B_L (red plus symbol), the B_M (green cross), and the B_N (blue asterisk) components of the magnetic field during the reconnection exhaust interval of (a) event 1, (b) event 2, (c) event 3, and (d) event 4. The full black circle, open red triangle, and full gray triangle represent the chaotic time series of the logistic map, the skew tent map, and the Hénon map, respectively (see the text for parameters). The crescent-shaped curves indicate the maximum and minimum values of C_J^S for a given value of H , and the dotted line represents stochastic fractional Brownian motion.

Table 2
The (H, C_J^S) Values of the B_L , B_M , and B_N Components of the Magnetic Field for $d = 4, 5$, and 6 , for Event 1

	$d = 4$		$d = 5$		$d = 6$	
	H	C_J^S	H	C_J^S	H	C_J^S
B_L	0.9361 ± 0.0002	0.0725 ± 0.0002	0.9089 ± 0.0001	0.1250 ± 0.0002	0.8751 ± 0.0002	0.1951 ± 0.0004
B_M	0.9599 ± 0.0005	0.0470 ± 0.0005	0.9400 ± 0.0005	0.0888 ± 0.0006	0.9114 ± 0.0007	0.1644 ± 0.0009
B_N	0.9769 ± 0.0001	0.0292 ± 0.0002	0.9631 ± 0.0001	0.0621 ± 0.0002	0.9416 ± 0.0002	0.1178 ± 0.0008

reliably due to the small number of data points. High-resolution data from instruments operating on higher cadence modes would be needed for the convergence of higher-order statistics. However, we have shown that similar results can be obtained by computing the J-S index. Since magnetic exhausts in the solar wind at 1 au usually have a short duration (EnŽl et al. 2014), the J-S index can be a useful tool for the analysis of the magnetic-field turbulence within exhausts.

The exhaust intervals in Table 1 were carefully defined to avoid including the strong discontinuities due to the magnetic-field reversal near the boundaries of the reconnection exhaust (see the time series of B_L in Figure 2). We have also applied a detrending technique to further remove large-scale variations of the time series (see Figure 3). Despite this, the higher degree of intermittency and complexity, and the lower degree of entropy, observed in the B_L as compared with the other components, can

still be due to the field reversal that occurs at a larger scale. Previous studies have pointed out evidence of a direct coupling between large-scale fluctuations and small-scale intermittency in the solar wind (Vörös et al. 2006; Miranda et al. 2018). Therefore, the inertial-range coherent structures in the B_L component within the reconnection exhaust can have their origin on the magnetic reconnection process that occurs at a larger scale. Note that this is in agreement with the main conclusion of Chian et al. (2016).

Our analysis of the three components of the magnetic field by the hybrid MVA suggests that intermittency and complexity-entropy vary with the field direction. Other characterizations of anisotropy in magnetic-field fluctuations in the solar wind, such as spectral anisotropy, have been demonstrated by several studies (e.g., Matthaeus et al. 1990; Dasso et al. 2005; Šafránková et al. 2021). In that context, spectral anisotropy

refers to the unequal distribution of energy between the wavevectors directed parallel and perpendicular to the mean magnetic field. Energy spectra computed using single-spacecraft data displays unequal distribution of energy among magnetic-field components, which is termed variance anisotropy. However, this anisotropy observed using single-spacecraft data is not sufficient to demonstrate spectral anisotropy, and must be interpreted with caution. For example, calculated variances from single-spacecraft data can be misleadingly anisotropic even in the presence of an isotropic distribution of energy (Oughton et al. 2015). A careful analysis of the variance anisotropy displayed by the energy spectra, and the different behavior of intermittency and complexity-entropy of magnetic-field components will be the focus of a future work.

In summary, in this paper, we analyzed the LMN components of the magnetic field at the exhaust of four reconnection events detected in the solar wind at 1 au. The link between intermittency and complexity within the inertial subrange was demonstrated for the first event by computing the scaling exponents and the J–S index. For the four events, all components have H and C_J^S values within the stochastic region of the C–H plane. The B_L component displays a higher degree of intermittency, lower entropy, and higher complexity than the B_M and the B_N components. Our results confirm that magnetic-field turbulence within reconnection exhausts are intermittent with various levels of multifractality in different directions, suggesting that nontrivial coherent structures are responsible for varying degrees of entropy and complexity. These results can contribute with additional constraints to the ongoing efforts on magnetic reconnection modeling and numerical simulation.

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